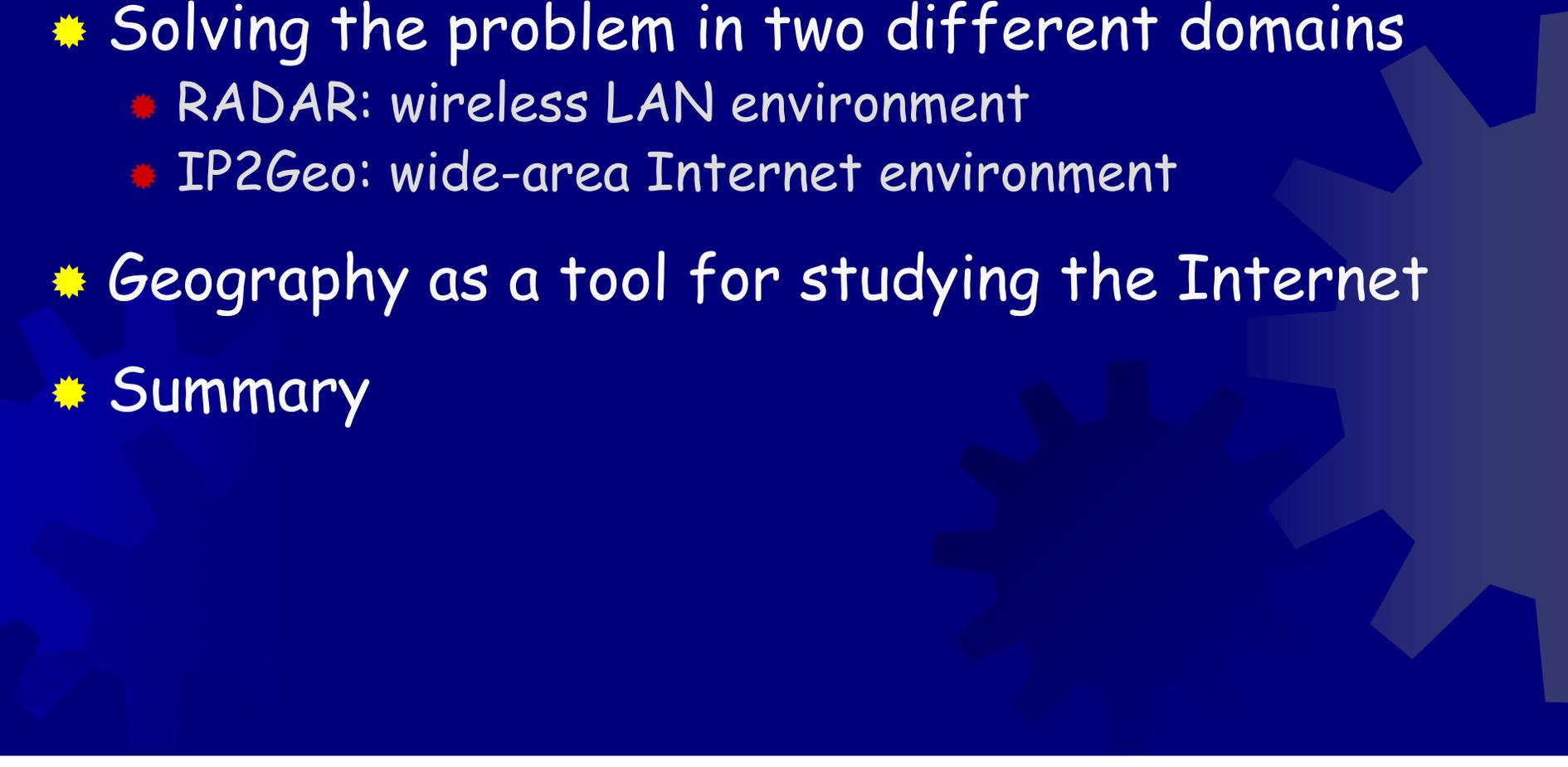


Locating Internet Hosts

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Harvard CS Colloquium
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Outline

- ★ Why is user or host positioning interesting?
 - ★ Solving the problem in two different domains
 - ★ RADAR: wireless LAN environment
 - ★ IP2Geo: wide-area Internet environment
 - ★ Geography as a tool for studying the Internet
 - ★ Summary
- 

Motivation

- ★ Location-aware services help users interact better with their environment
 - ★ Navigational services (in-building, metro area)
 - ★ Resource location (nearest restaurant, nearest printer)
 - ★ Targeted advertising (sales, election canvassing)
 - ★ Notification services (buddy alert, weather alert)
- ★ User positioning is a prerequisite to location-aware services
- ★ But this is a challenging problem

Our Work

- ★ We have built host location systems for two different environments
 - ★ RADAR: wireless LANs
 - mobile clients (laptops, PDAs) that connect via a wireless LAN
 - typically within buildings
 - ★ IP2Geo: wide-area Internet
 - typically fixed hosts (e.g., desktop machines, home PCs)
- ★ Goal: leverage existing infrastructure

RADAR

(Joint work with P. Bahl and A. Balachandran)

Background

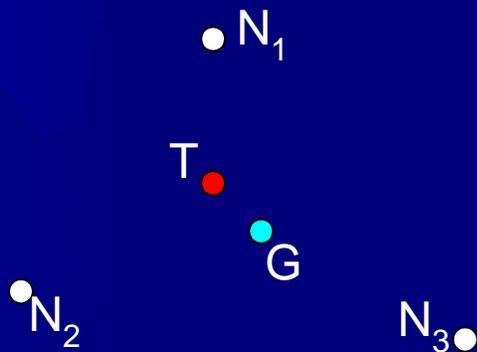
- ★ Focuses on the indoor environment
- ★ Limitations of current solutions
 - ★ global positioning system (GPS) does not work indoors
 - ★ line-of-sight operation (e.g., IR-based Active Badge)
 - ★ dedicated technology (e.g., ultrasound-based Bats)
- ★ Our goal: leverage *existing* infrastructure
 - ★ use off-the-shelf RF-based wireless LAN
 - ★ intelligence in software
 - ★ better scalability and lower cost than dedicated technology

RADAR Basics

- ★ Key idea: signal strength matching
- ★ Offline calibration:
 - tabulate $\langle \text{location}, SS \rangle$ to construct *radio map*
 - empirical method or mathematical method
- ★ Real-time location and tracking:
 - extract SS from base station beacons
 - find table entry that best matches the measured SS
- ★ Benefits:
 - little additional cost
 - no line-of-sight restriction \Rightarrow better scaling
 - autonomous operation \Rightarrow user privacy maintained

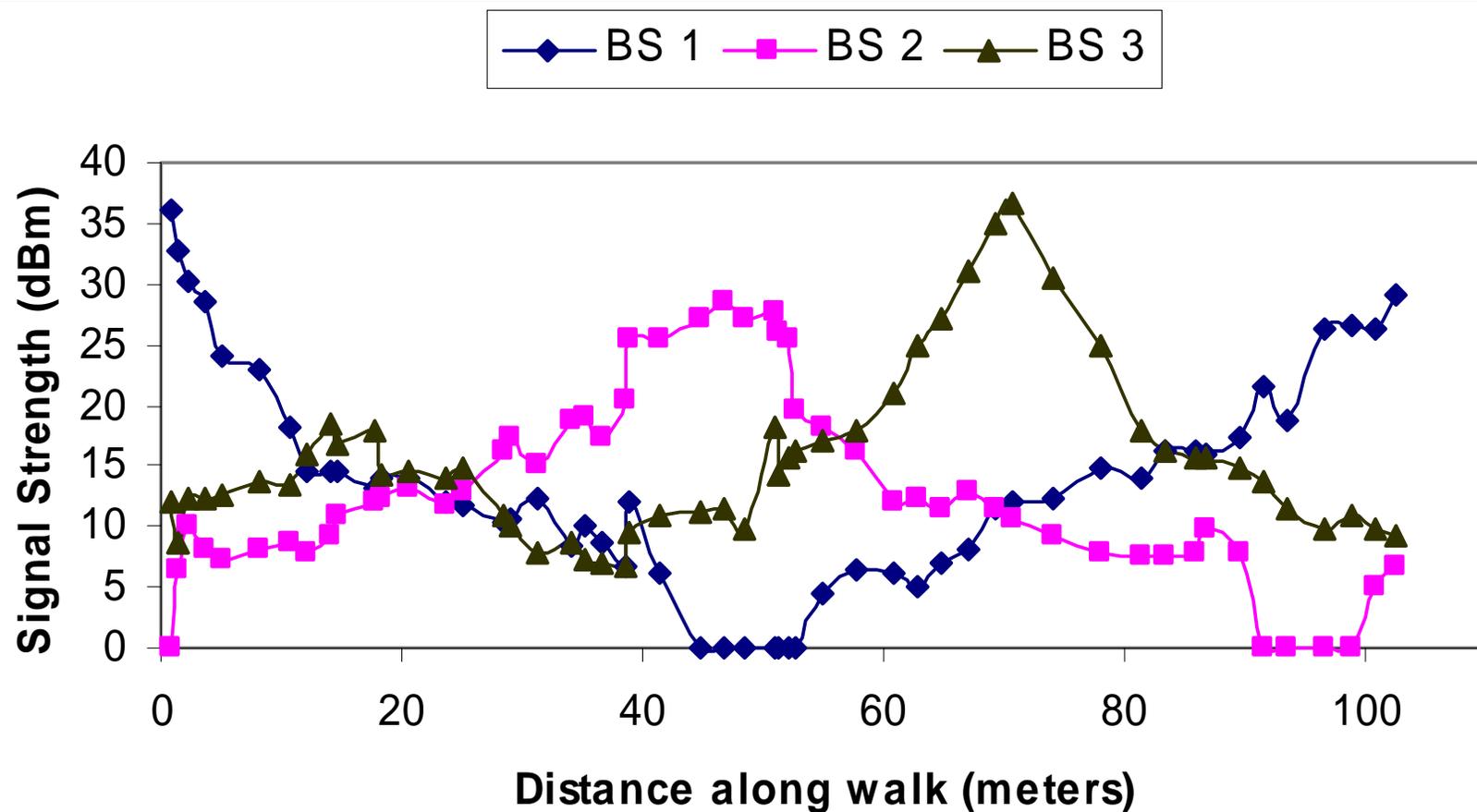
Determining Location

- ★ Find *nearest neighbor in signal space* (NNSS)
 - ★ default metric is Euclidean distance
- ★ Physical coordinates of NNSS \Rightarrow user location
- ★ Refinement: k -NNSS
 - ★ average the coordinates of k nearest neighbors

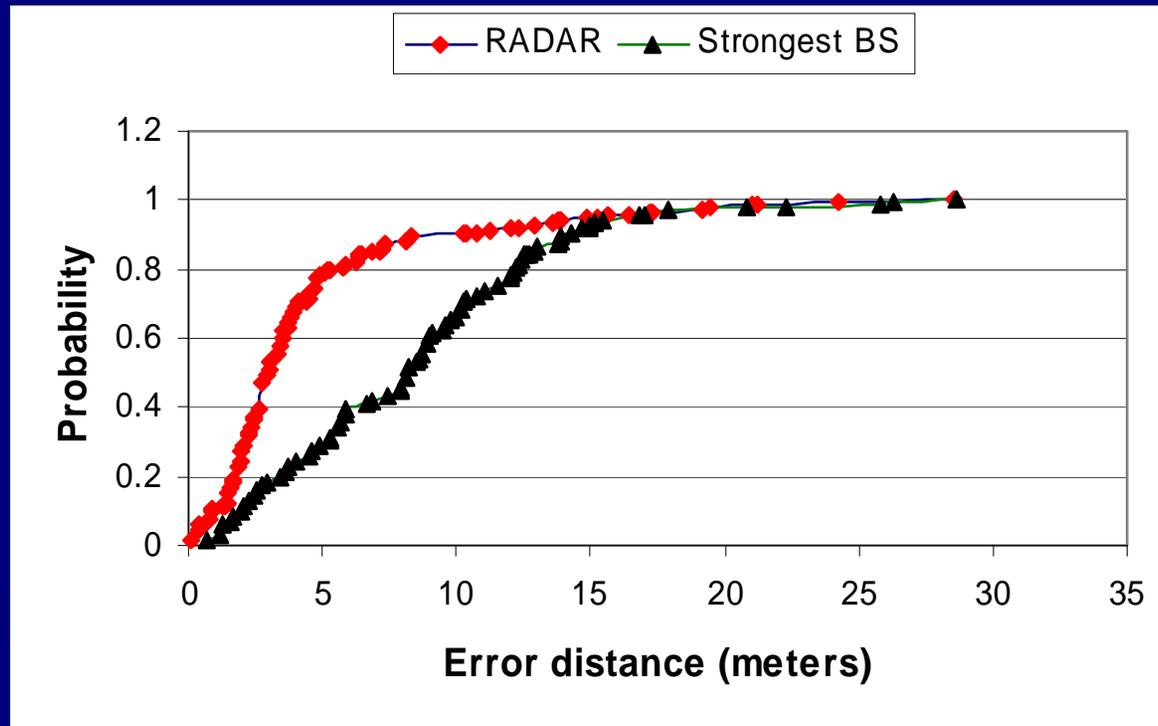


N_1, N_2, N_3 : neighbors
 T : true location of user
 G : guess based on averaging

How well does signal strength correlate with location?



RADAR Performance



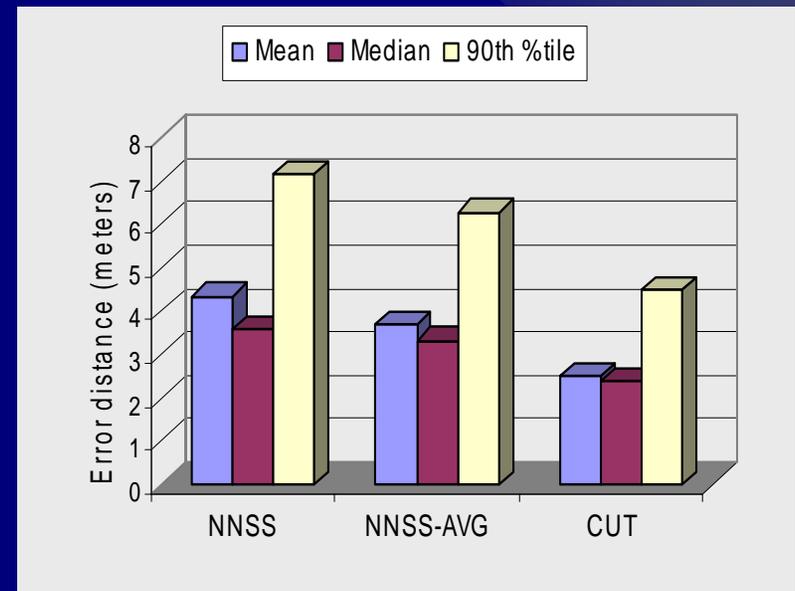
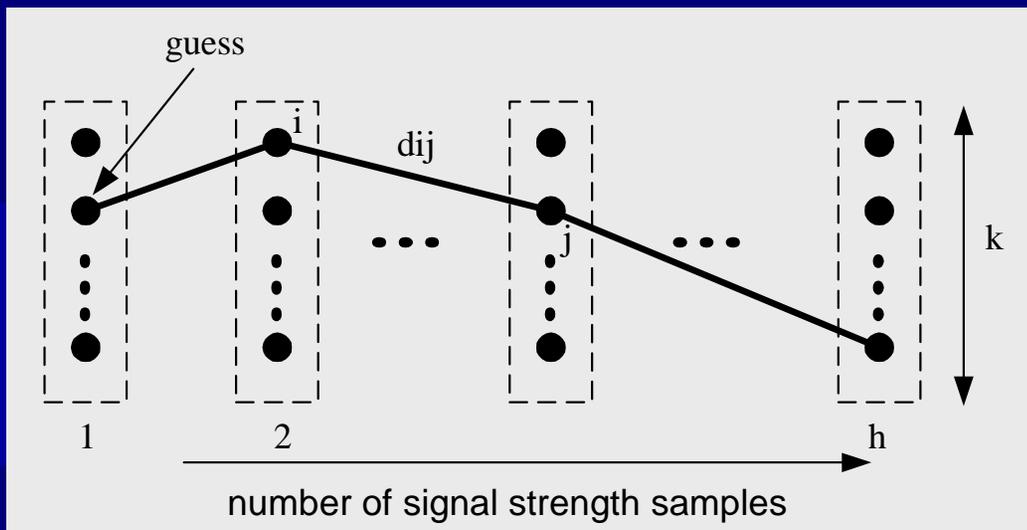
Median error distance is 2.94 m. Averaging ($k=3$) brings this down to 2.13 m

Dynamic RADAR System

- ✦ Enhances the base system in several ways
 - ✦ mobile users
 - ✦ changes in the radio propagation environment
 - ✦ multiple radio channels
- ✦ DRS incorporates new algorithms
 - ✦ continuous user tracking
 - ✦ environment profiling
 - ✦ channel switching

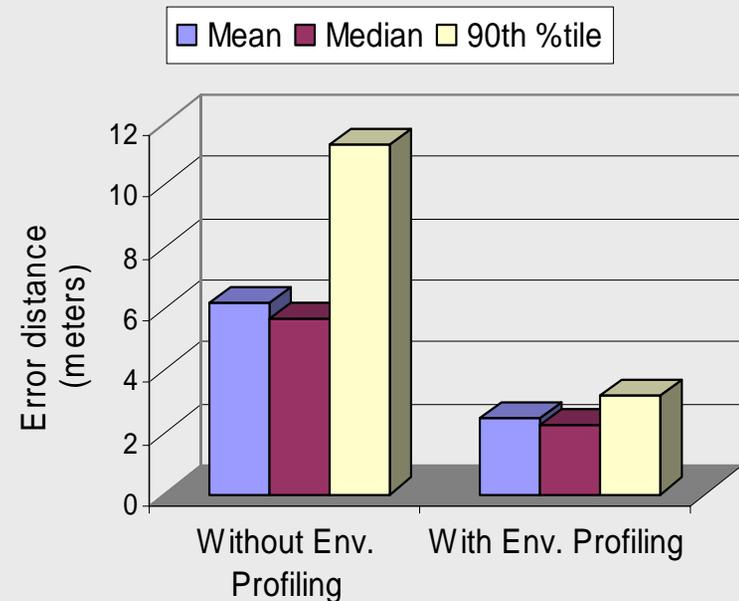
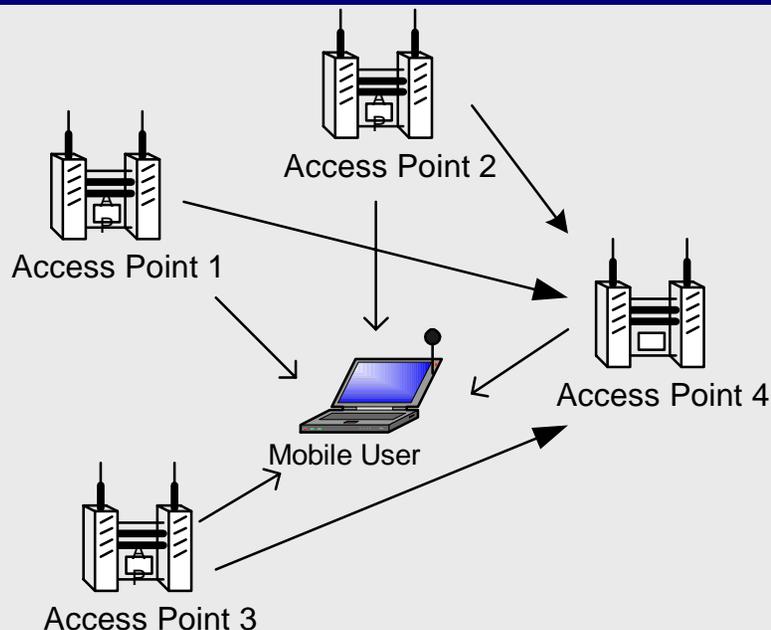
Continuous User Tracking

- ☀ History-based model that captures physical constraints
- ☀ Find the lowest cost path (à la Viterbi algorithm)
- ☀ Addresses the problem of *signal strength aliasing*



Environment Profiling

- Addresses problem of changing RF environment
- System maintains multiple radio maps
- Maps indexed by environment profiles created by APs
- APs probe the environment and pick the best map

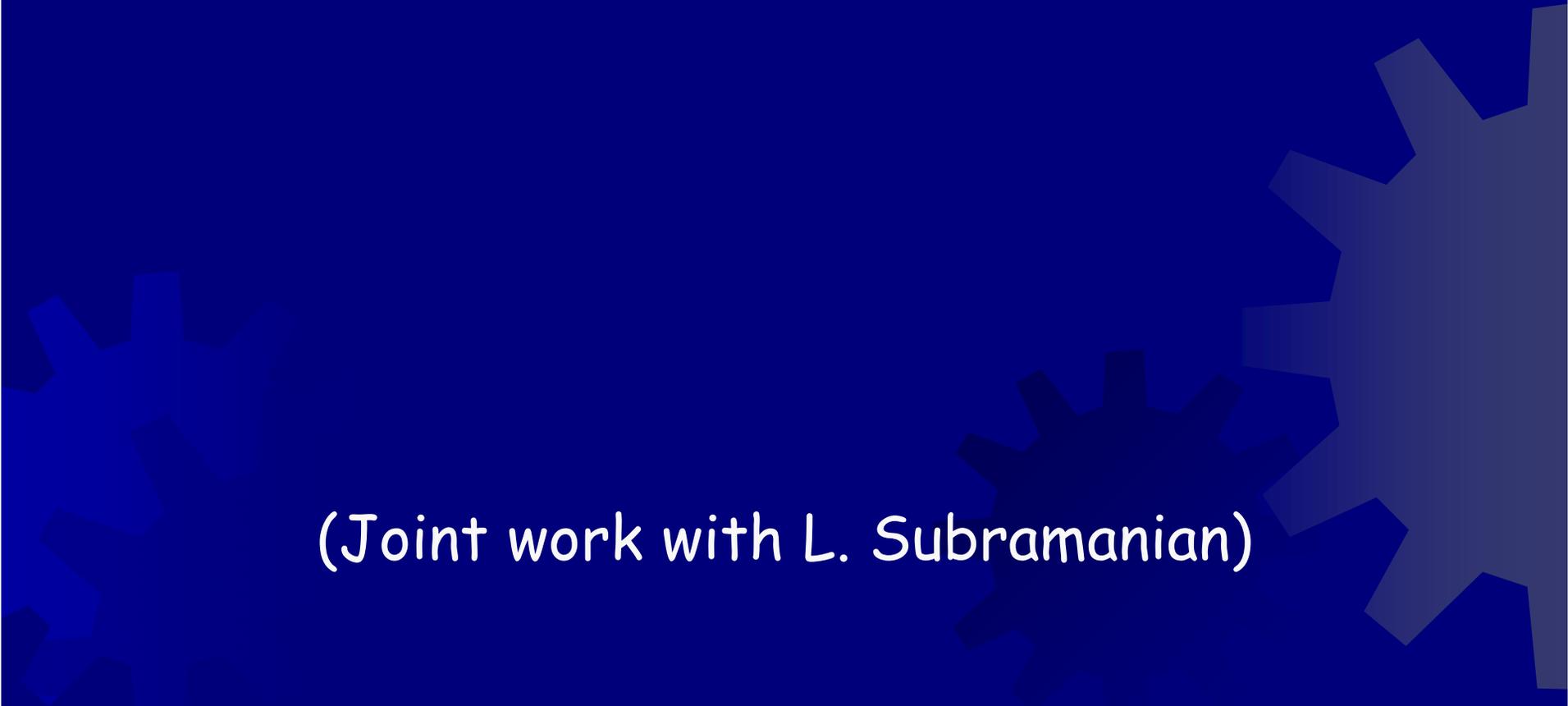


Summary of RADAR

- ★ RADAR: a software approach to user positioning
 - leverages existing wireless LAN infrastructure \Rightarrow low cost
 - enables autonomous operation \Rightarrow user privacy maintained
- ★ Base system
 - radio map constructed either empirically or mathematically
 - NNS algorithm matches signal strength against the radio map
- ★ Enhanced system
 - continuous user tracking
 - environment profiling
- ★ Median error: ~ 2 meters
- ★ Publications:
 - Base system: INFOCOM 2000 paper
 - Enhanced system: Microsoft Technical Report MSR-TR-2000-12

IP2Geo

(Joint work with L. Subramanian)



Motivation

- ★ Much focus on location-aware services in wireless and mobile contexts
- ★ Such services are relevant in the Internet context too
 - targeted advertising
 - event notification
 - territorial rights management
 - network diagnostics
- ★ Locating the user or host is a prerequisite
- ★ But this is a challenging problem
 - IP address does not inherently contain an indication of location

Existing Approaches

- ☀ User input
 - burdensome, error-prone
- ☀ User registration/cookies: e.g., Hotmail
 - better, but many services do not require the user to log in
 - cookie information may not be always available
 - registered location may be incorrect or stale
- ☀ *Whois* database: e.g., NetGeo
 - registered location may correspond to headquarters
 - manual updates, inconsistent databases
- ☀ Proprietary technology
 - Traceware (Digital Island), EdgeScape (Akamai)
 - country/state resolution
 - exhaustive tabulation of IP address space exploiting view from within ISP networks?

IP2Geo

Multi-pronged approach that exploits various "properties" of the Internet

- DNS names of router interfaces often indicate location
- network delay tends to correlate with geographic distance
- hosts that are aggregated for the purposes of Internet routing also tend to be clustered geographically

★ *GeoTrack*

- determine location of closest router with a recognizable DNS name

★ *GeoPing*

- use delay measurements to estimate location

★ *GeoCluster*

- extrapolate partial (and possibly inaccurate) IP-to-location mapping information using BGP prefix clusters

GeoTrack

- ☀ Location info often embedded in router DNS names
 - ngcore1-serial8-0-0-0.Seattle.cw.net, 184.atm6-0.xr2.ewr1.alter.net
- ☀ GeoTrack operation
 - do a *traceroute* to the target IP address
 - determine location of last recognizable router along the path
- ☀ Key ideas in GeoTrack
 - partitioned city code database to minimize chance of false match
 - ISP-specific parsing rules
 - delay-based correction
- ☀ Limitations
 - routers may not respond to *traceroute*
 - DNS name may not contain location information or lookup may fail
 - target host may be behind a proxy or a firewall

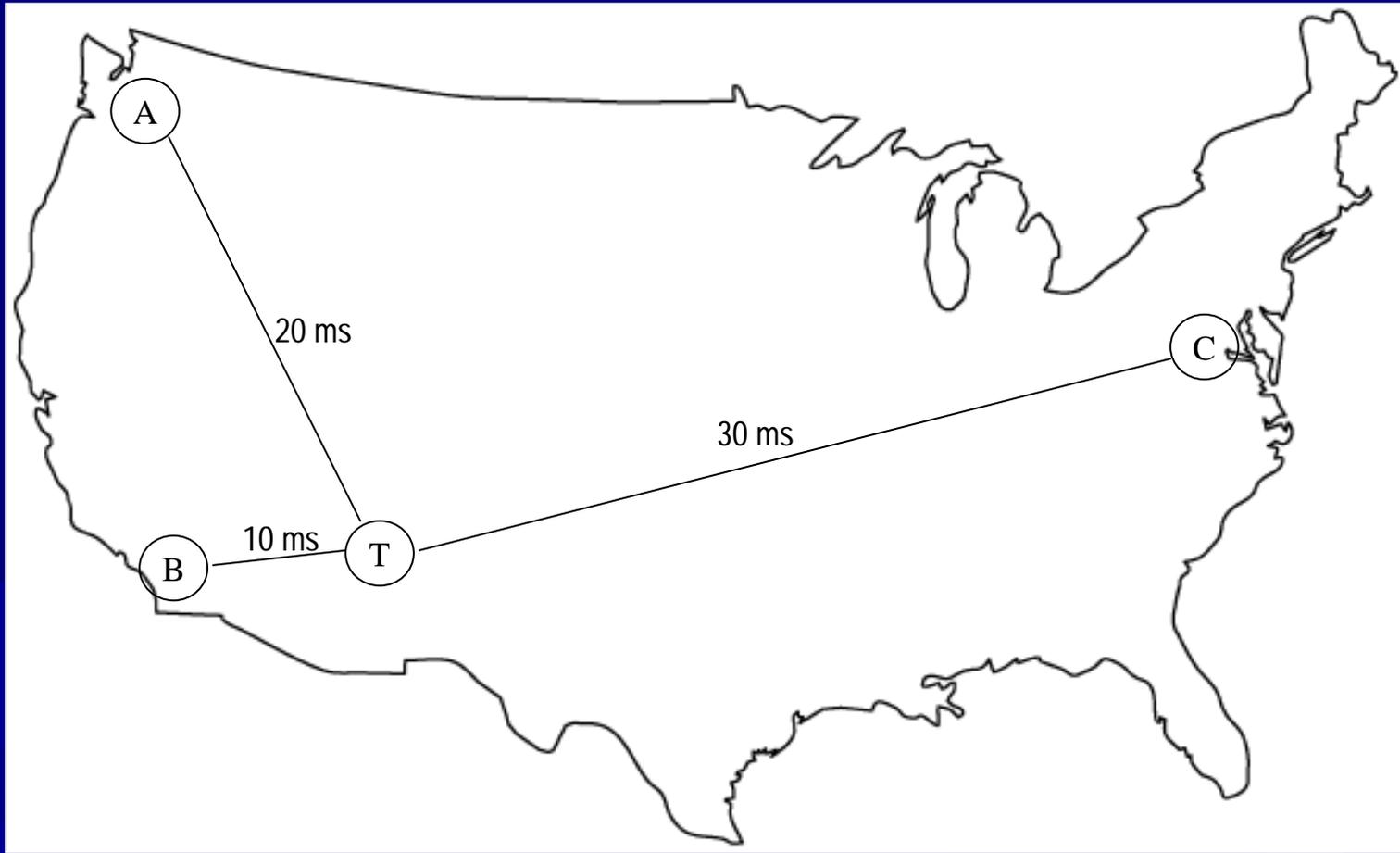
GeoTrack Example

Traceroute from Berkeley to Dartmouth

snr46.CS.Berkeley.EDU	Berkeley,CA	UnitedStates
gig10-cnr1.EECS.Berkeley.EDU	Berkeley,CA	UnitedStates
gigE5-0-0.inr-210-cory.Berkeley.EDU	Berkeley,CA	UnitedStates
fast1-0-0.inr-001-eva.Berkeley.EDU	Berkeley,CA	UnitedStates
pos0-0.inr-000-eva.Berkeley.EDU	Berkeley,CA	UnitedStates
pos3-0.c2-berk-gsr.Berkeley.EDU	Berkeley,CA	UnitedStates
SUNV--BERK.POS.calren2.net	Sunnyvale,CA	UnitedStates
abilene--QSV.POS.calren2.net	Sunnyvale,CA	UnitedStates
dnvr-scrm.abilene.ucaid.edu	Denver,CO	UnitedStates
kscy-dnvr.abilene.ucaid.edu	KansasCity,MO	UnitedStates
ipls-kscy.abilene.ucaid.edu	Indianapolis,IN	UnitedStates
clev-ipls.abilene.ucaid.edu	Cleveland,OH	UnitedStates
nycm-clev.abilene.ucaid.edu	NewYork,NY	UnitedStates
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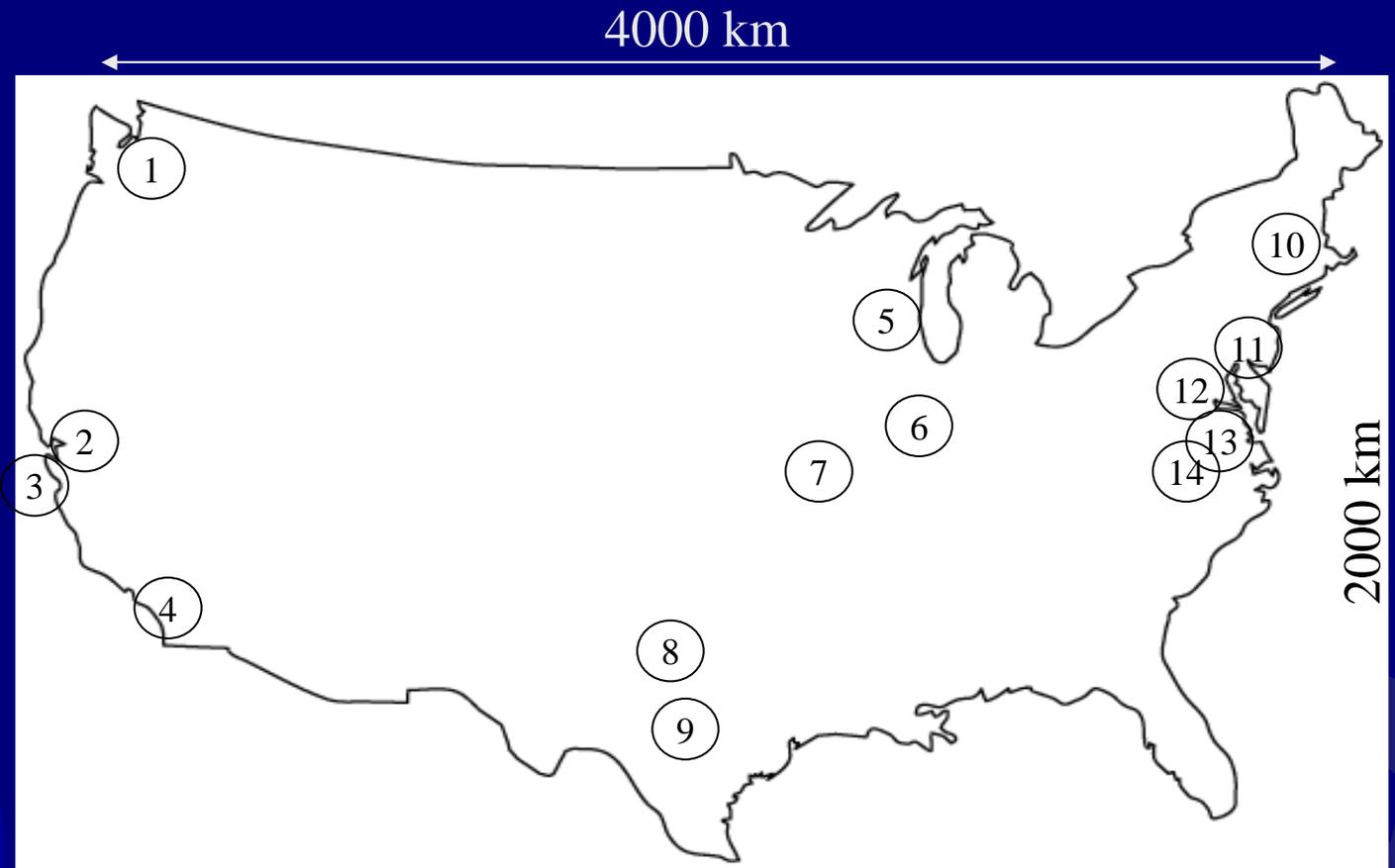
Delay-based Location Estimation

- ★ Delay-based triangulation is conceptually simple
 - delay \Rightarrow distance
 - distance from 3 or more non-collinear points \Rightarrow location
- ★ But there are practical difficulties
 - network path may be circuitous
 - transmission & queuing delays may corrupt delay estimate
 - one-way delay is hard to measure
 - one-way delay \neq round-trip delay/2 because of routing asymmetry



GeoPing

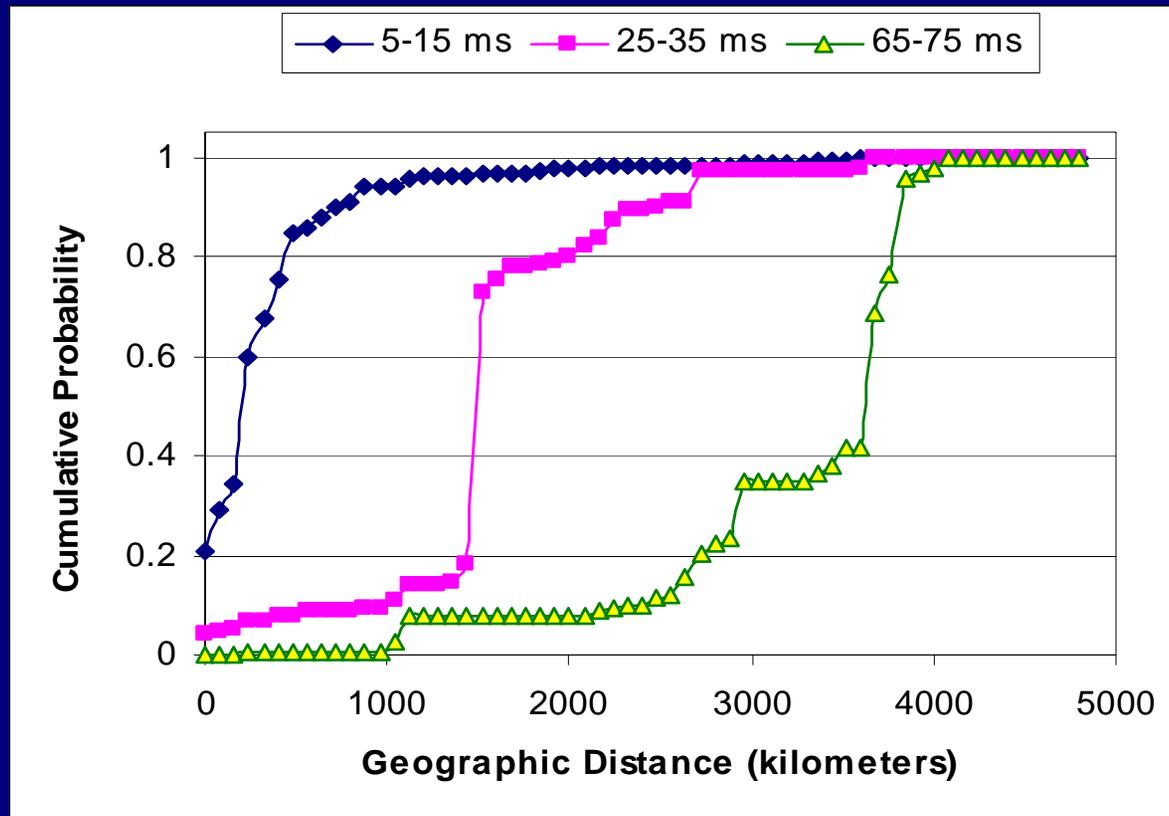
- ☀ Measure the network delay to the target host from several geographically distributed *probes*
 - typically more than 3 probes are used
 - round-trip delay measured using *ping* utility
 - small-sized packets \Rightarrow transmission delay is negligible
 - pick minimum among several delay samples
- ☀ *Nearest Neighbor in Delay Space (NNDS)*
 - akin to Nearest Neighbor in Signal Space (NNSS) in RADAR
 - construct a *delay map* containing (delay vector, location) tuples
 - given a vector of delay measurements, search through the delay map for the NNDS
 - location of the NNDS is our estimate for the location of the target host
 - More robust than directly trying to map from delay to distance



- | | | | |
|-----------------|-----------------|---------------------|-------------------|
| ① Redmond, WA | ⑤ Madison, WI | ⑨ Austin, TX | ⑬ Durham, NC |
| ② Berkeley, CA | ⑥ Urbana, IL | ⑩ Boston, MA | ⑭ Chapel Hill, NC |
| ③ Stanford, CA | ⑦ St. Louis, MO | ⑪ New Brunswick, NJ | |
| ④ San Diego, CA | ⑧ Dallas, TX | ⑫ Baltimore, MD | |

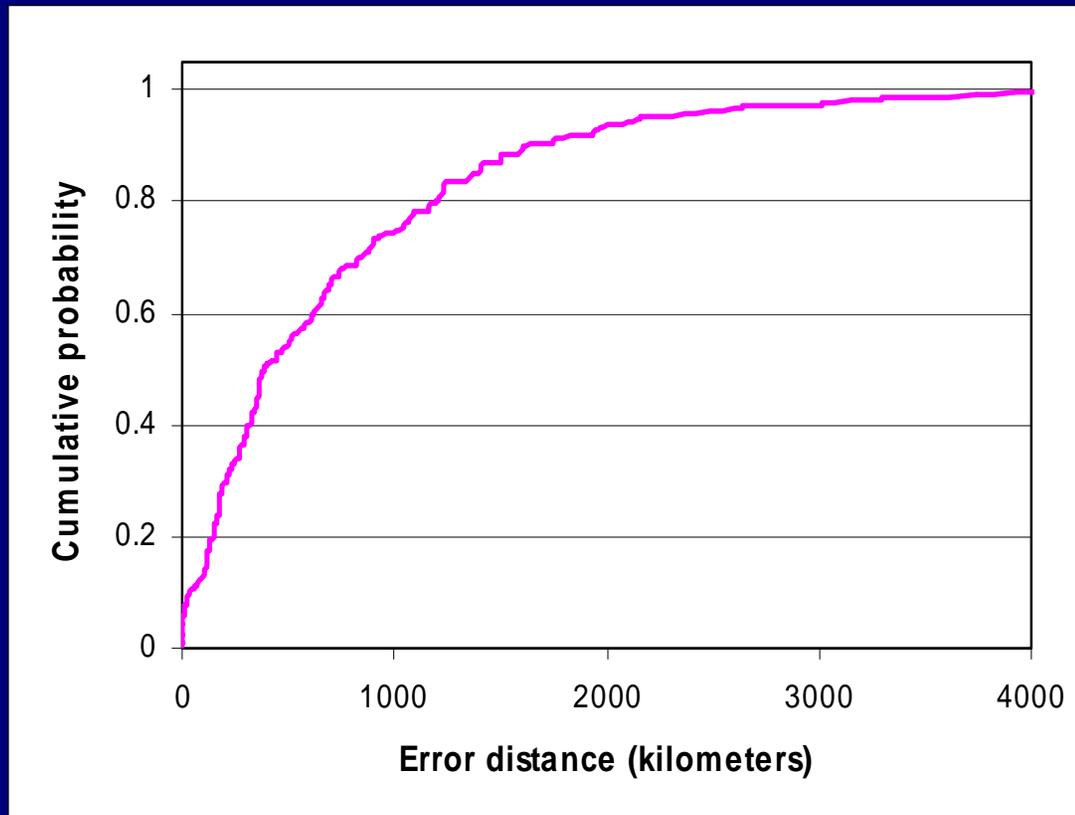
Delay map constructed using measured delays to 265 hosts on university campuses

Validation of Delay-based Approach



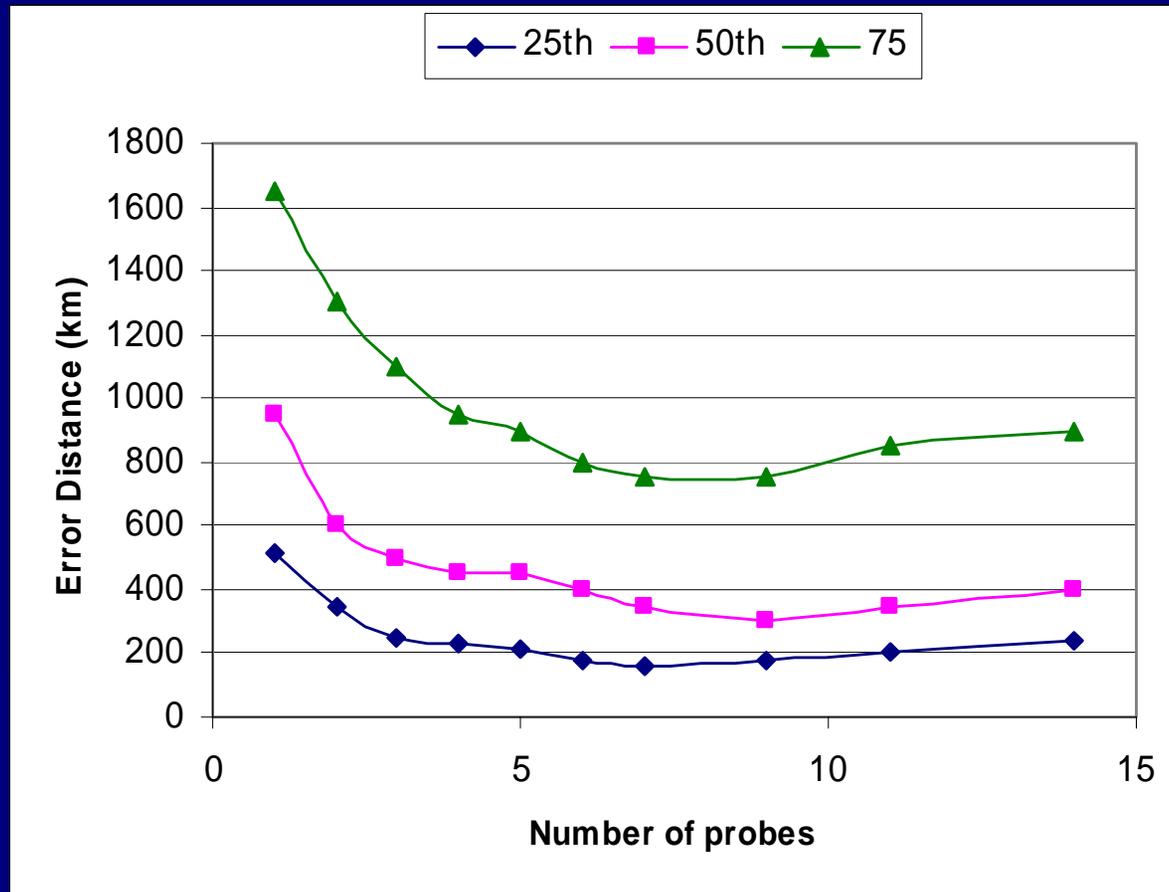
Delay tends to increase with geographic distance

Performance of GeoPing



9 probes used. Error distance: 177 km (25th), 382 km (50th), 1009 km (75th)

Performance of GeoPing



Highest accuracy when 7-9 probes are used

GeoCluster

- ★ A passive technique unlike GeoTrack and GeoPing
- ★ Basic idea:
 - divide up the space of IP addresses into *clusters*
 - extrapolate *partial* IP-to-location mapping information to assign a location to each cluster
 - given a target IP address, first find the matching cluster using longest-prefix match.
 - location of matching cluster is our estimate of host location
- ★ Example:
 - consider the cluster 128.95.0.0/16 (containing 65536 IP addresses)
 - suppose we know that the location corresponding to a few IP addresses in this cluster is Seattle
 - then given a new address, say 128.95.4.5, we deduce that it is likely to be in Seattle too

Clustering IP addresses

- ✦ Exploit the hierarchical nature of Internet routing
 - ✦ we use the approach proposed by Krishnamurthy & Wang (SIGCOMM 2000)
 - ✦ inter-domain routing in the Internet uses the *Border Gateway Protocol* (BGP)
 - ✦ BGP operates on address aggregates
 - ✦ we treat these aggregates as clusters
 - ✦ in all we had about 100,000 clusters of different sizes

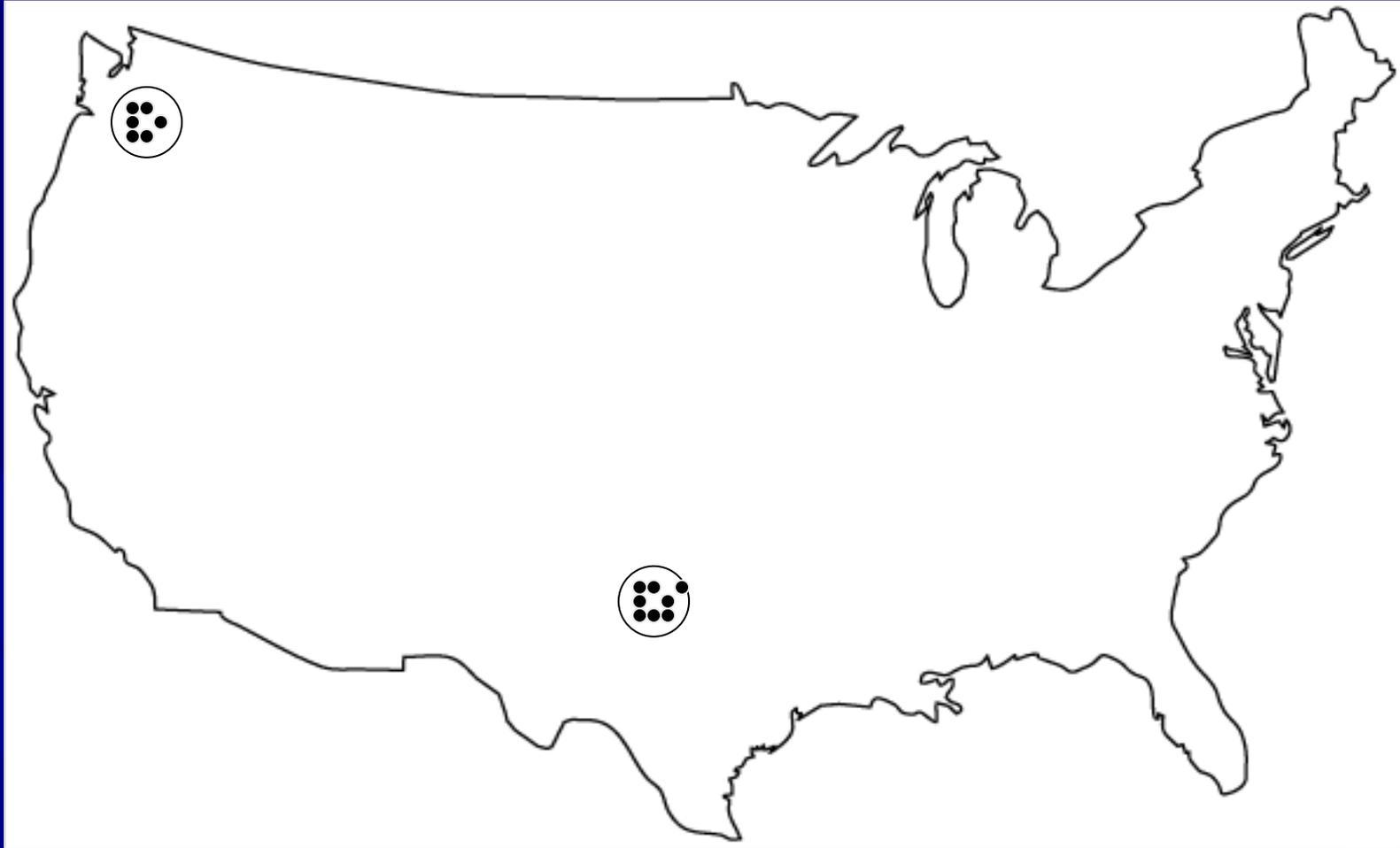
IP-to-location Mapping

- ★ IP-to-location mapping information
 - *partial* information (i.e., only for a small subset of addresses)
 - possibly *inaccurate* (e.g., manual input from user)
- ★ We obtained mapping information from a variety of sources
 - *Hotmail*: combined anonymized user registration information with client IP address
 - *Online TV guide*: combined zip code submitted in user query with client IP address
 - *bCentral*: derived location information from cookies
- ★ How would this information be obtained in general?
 - likely location (not necessarily accurate) may be inferred from user queries (e.g., TV guide)
 - location information from small number of registered users could be extrapolated to a much larger number of casual users

Extrapolating IP-to-location Mapping

- ✦ Determine location most likely to correspond to a cluster
 - majority polling
 - "average" location
 - *dispersion* is an indicator of our confidence in the location estimate
- ✦ What if there is a large geographic spread in locations?
 - some clusters correspond to large ISPs and the internal subdivisions are not visible at the BGP level
 - *sub-clustering algorithm*: keep sub-dividing clusters until there is sufficient consensus in the individual sub-clusters
 - some clients connect via proxies or firewalls (e.g., AOL clients)
 - sub-clustering may help if there are local or regional proxies
 - otherwise large dispersion \Rightarrow no location estimate made
 - many tools fail in this regard

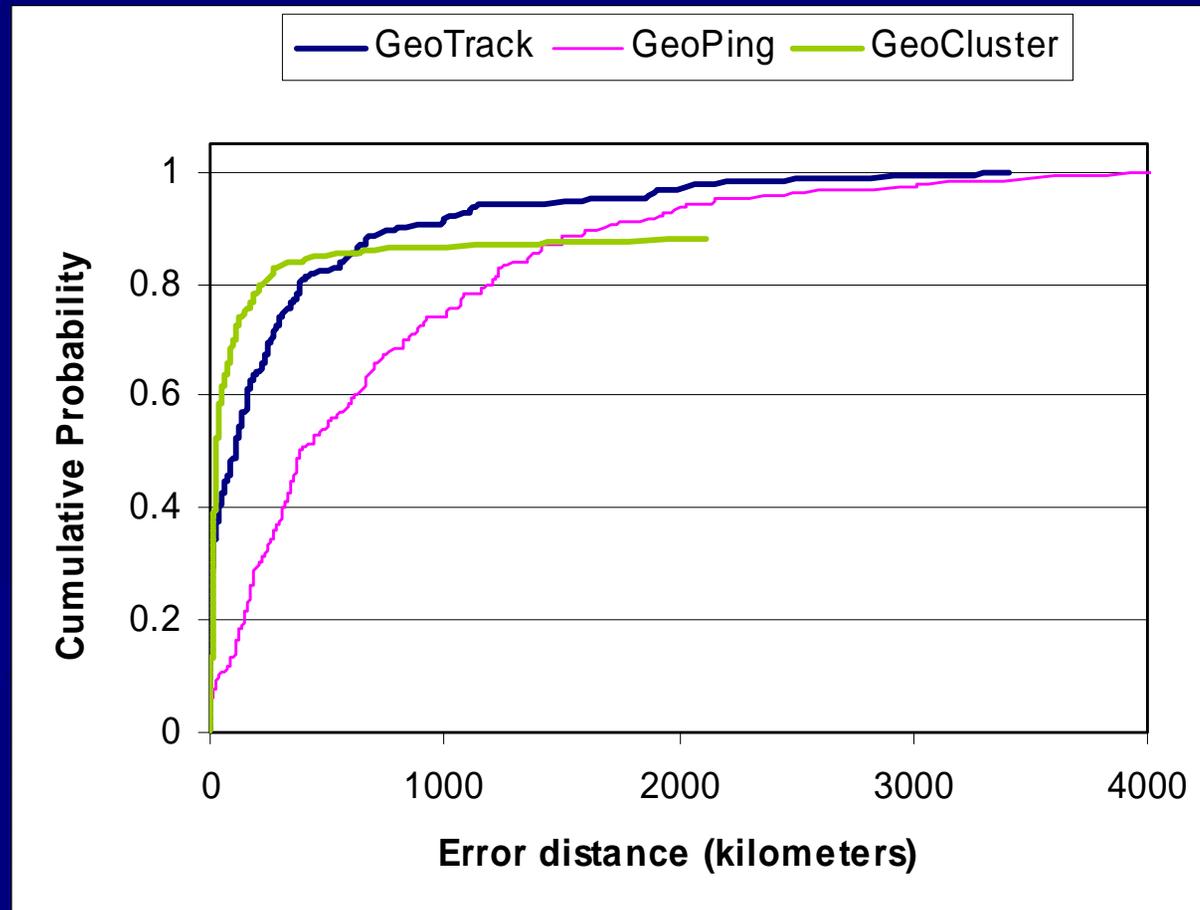
Geographically Localized Clusters



Geographically Dispersed Clusters



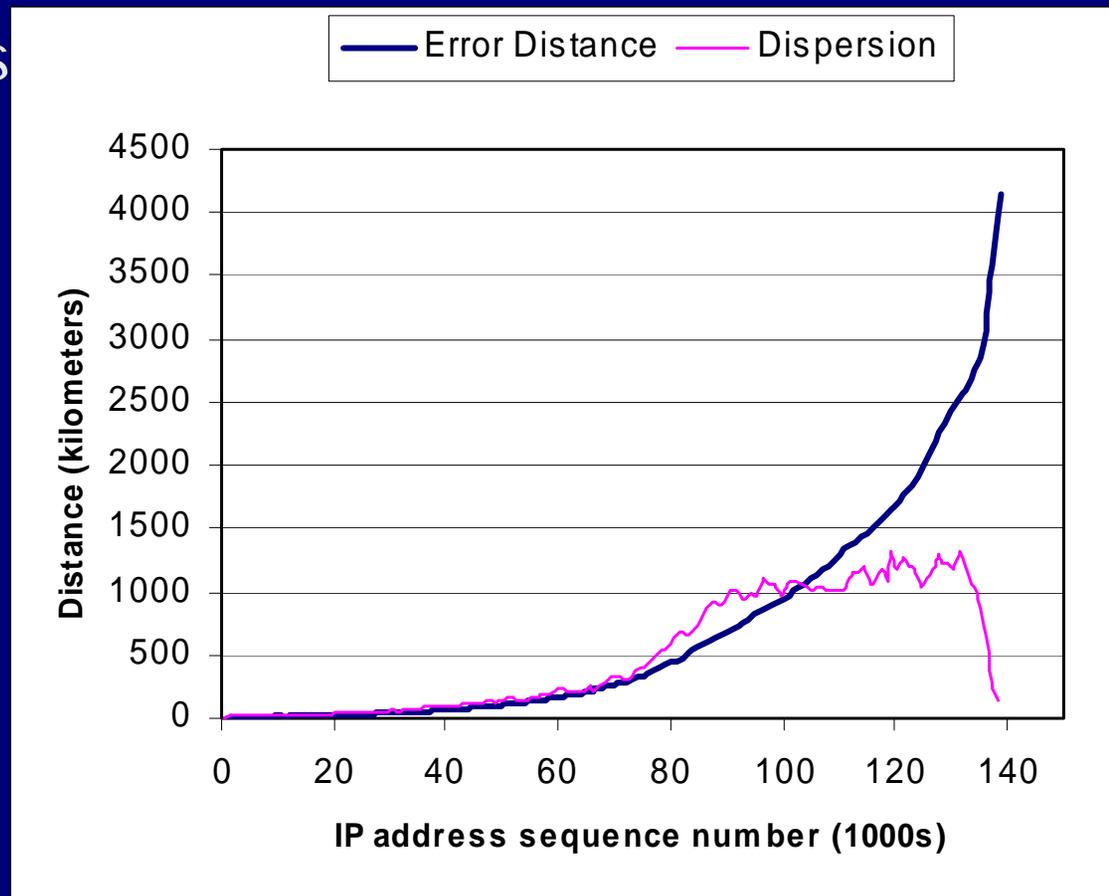
Performance of GeoCluster



Median error: GeoTrack: 102 km, GeoPing: 382 km, GeoCluster: 28 km

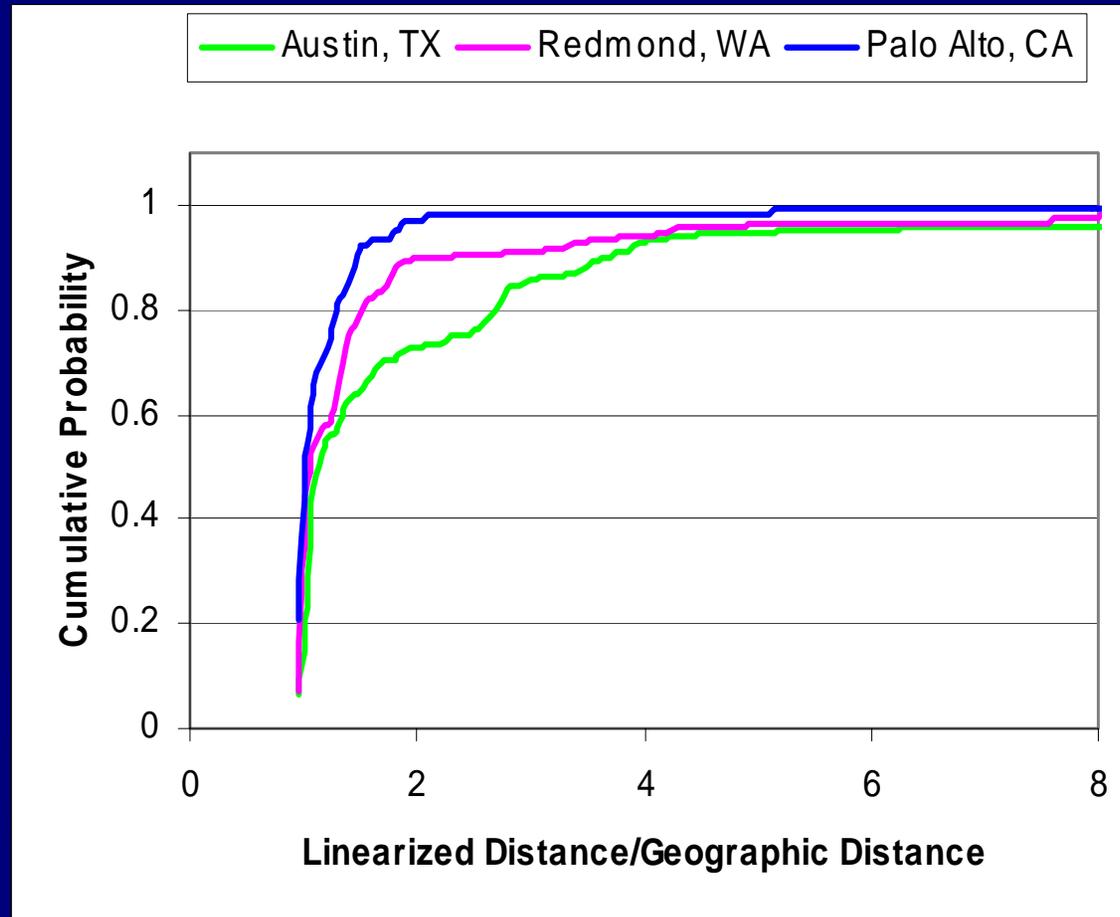
Performance of GeoCluster

bCentral clients



Dispersion is on average a good indicator of accuracy

Using IP2Geo to Study Internet connectivity



Path from TX to KY: TX → CA → NJ → IN → KY

Summary of IP2Geo

- ★ A variety of techniques that depend on different sources of information
 - ★ GeoTrack: DNS names
 - ★ GeoPing: network delay
 - ★ GeoCluster: address aggregates used for routing
- ★ Median error varies 20-400 km
- ★ Even a 30% success rate is useful especially since we can tell when the estimate is likely to be accurate
- ★ Paper to appear in ACM SIGCOMM 2001

Conclusions

- ★ RADAR and IP2Geo try to solve the same problem in very different contexts
 - ★ wireless versus wireline
 - ★ indoor environment versus global scale
 - ★ accuracy of a few meters versus tens or hundreds of kilometers
- ★ Interesting but challenging problem!
- ★ For more information visit:
<http://www.research.microsoft.com/~padmanab/>